Optimal designs and root systems



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The incidence matrix N of the block design is the $v \times b$ matrix with (p, b) entry 1 if $p \in B$, 0 otherwise. The matrix $\Lambda = NN^{\top}$ is the concurrence matrix, with (p, q) entry equal to the number of blocks containing p and q. It is symmetric, with row and column sums rk, and diagonal entries r.

The information matrix of the block design is $L = rI - \Lambda/k$. It has a "trivial" eigenvalue 0, corresponding to the all-1 eigenvector.

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A 2-design is optimal in all three senses. But what if no 2-design exists for the given v, k, r?

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The question

For a 2-design, the concurrence matrix is $\Lambda = (r - \lambda)I + \lambda J$, where *J* is the all-1 matrix. Ching-Shui Cheng suggested looking for designs where Λ is a small perturbation of this, say $\Lambda = (r - t)I + tJ - A$, where *A* is a matrix with small entries (say 0, +1, -1). For E-optimality, we want *A* to have smallest eigenvalue as large as possible (say greater than -2).

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Call such a matrix admissible.

If *A* is admissible, then 2I + A is positive definite, so is a matrix of inner products of a set of vectors in \mathbb{R}^n .

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These vectors form a subsystem of a root system of type A_n , D_n , E_6 , E_7 or E_8 (as in the classification of simple Lie algebras by Cartan and Killing). Indeed, they form a basis for the root system.

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So we try to determine the admissible matrices by looking for subsets of the root systems.

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So an admissible matrix of this type is represented by a tree with oriented edges. (We have an edge $j \rightarrow i$ if $e_i - e_j$ is in our subset.)

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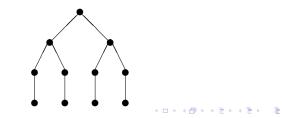
An oriented tree gives an admissible matrix if and only if s(w) - s(v) = c + 2 for any edge $v \rightarrow w$, where s(v) is the signed degree (number of edges in minus number out) and c is the constant row sum.

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Here is an example (edges directed upwards).



The vectors of D_n are those of the form $\pm e_i \pm e_j$ for $1 \le i < j \le n$, where e_1, \ldots, e_n form an orthonormal basis for \mathbb{R}^n .

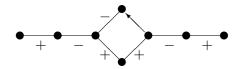
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Here is an example:



There are three exceptional root systems not of the above form, in 6, 7 and 8 dimensions, called E_6 , E_7 and E_8 .

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Here is an example in E_8 :

$$\begin{pmatrix} 0 & - & + & + & - & - & + & - \\ - & 0 & - & - & + & + & - & + \\ + & - & 0 & + & - & - & 0 & 0 \\ + & - & + & 0 & - & - & 0 & 0 \\ - & + & - & - & 0 & + & 0 & 0 \\ - & + & - & - & + & 0 & 0 & 0 \\ + & - & 0 & 0 & 0 & 0 & 0 & - \\ - & + & 0 & 0 & 0 & 0 & - & 0 \end{pmatrix}$$

Conclusion

Having determined the matrices, we can use Leonard Soicher's DESIGN software to look for block designs. Many examples exist.

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An example in E_6 has point set {1, 2, 3, 4, 5, 6} and blocks

{123, 125, 125, 134, 136, 136, 146, 156, 234, 245, 246, 246, 256, 345, 345, 356}.

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The next step would be to go on and decide whether any E-optimal block designs are obtained in this way. This has not yet been done!