

The ADE affair

Peter J. Cameron
University of St Andrews



UBI, Covilhã
October 2022

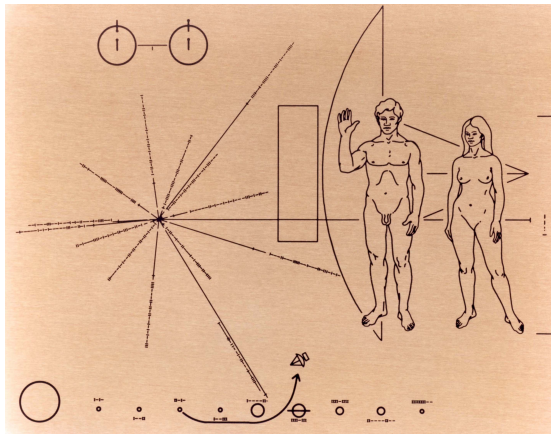
Calling card

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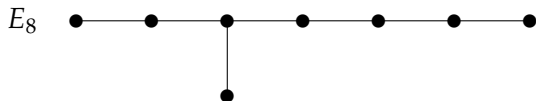
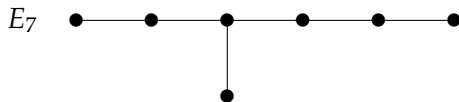
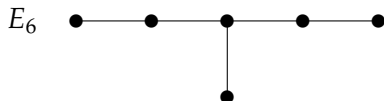
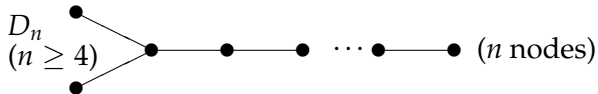
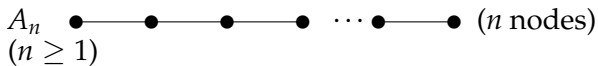
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The Pioneer engineers decided that this would do:



Francis Buekenhout had another idea:



A modern Hilbert problem?

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- ▶ ... the Coxeter groups generated by reflections, or of Weyl groups with roots of equal length.

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Buekenhout's view was that, even if an alien civilisation had very different mathematics to ours, chances are that they would have come up with at least some of the areas in which the ADE diagrams occur.

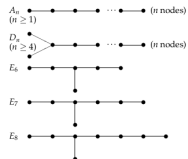
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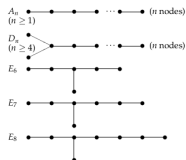
I will say a bit about some of this rich tapestry.

The extended diagrams



Closely related to the ADE diagrams are the so-called **extended diagrams**. In each case the extension adds one vertex, as follows:

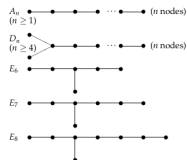
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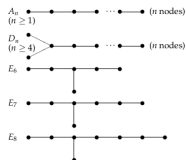
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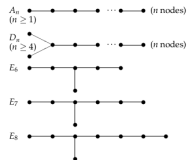
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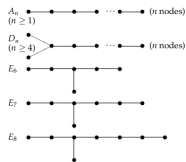
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- ▶ for D_n , it creates a fork at the other end of the diagram, or a $K_{1,4}$ if $n = 4$;
- ▶ for E_n , it extends one of the arms, so that the numbers of vertices on the arms are $(3, 3, 3)$ ($n = 6$), $(2, 4, 4)$ ($n = 7$), or $(2, 3, 6)$ ($n = 8$).

What are these diagrams?



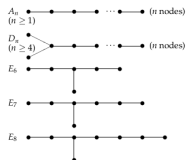
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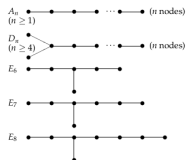


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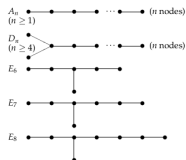


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Although this theorem was proved in 1969, it is in some sense implicit in the classification of simple Lie algebras over \mathbb{C} .

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It is easy to see that the extended ADE diagrams have greatest eigenvalue 2, as we will see shortly. So a connected graph whose greatest eigenvalue is less than 2 cannot contain any of these.

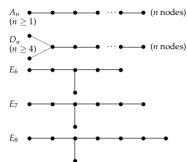
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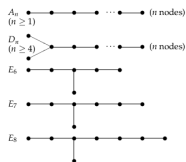
In particular, it does not contain \tilde{A}_n (a cycle), and so is a tree; it does not contain \tilde{D}_n , and so has at most one branchpoint, such a point having valency at most 3; and it does not contain \tilde{E}_n , and so the lengths of the three arms are restricted to the appropriate values.

Polyhedra and tessellations



The numbers of vertices on the arms of the E_n diagrams are $(2, 3, 3)$, $(2, 3, 4)$ and $(2, 3, 5)$ for $n = 6, 7, 8$ respectively. This should remind you of the regular polyhedra in 3-space.

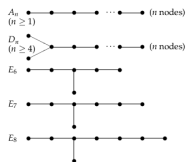
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The corresponding numbers for the extended diagrams are, as we saw, $(3, 3, 3)$, $(2, 4, 4)$ and $(2, 3, 6)$ respectively, corresponding to the regular tessellations of the Euclidean plane by triangles, squares and hexagons.

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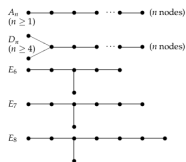


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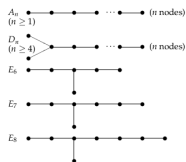
These are not accidental; we will return to them later.

A detour



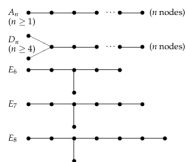
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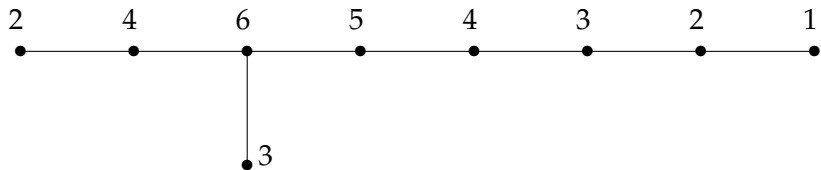
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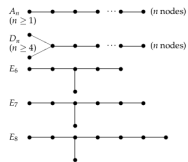


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An eigenvector

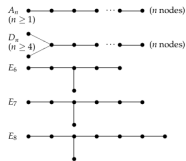


Finite rotation groups



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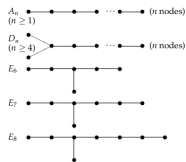
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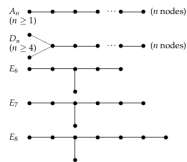
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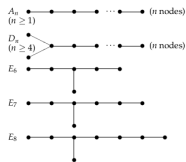
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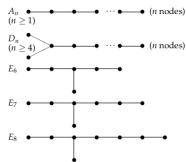
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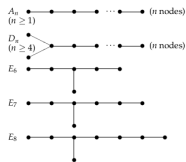
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The correspondence with the ADE diagrams is clear.

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The inverse image of each finite rotation group $G \leq SO_3(\mathbb{R})$ is a **double cover** \tilde{G} of G in $SU_2(\mathbb{C})$, a group with a centre Z of order 2 such that $\tilde{G}/Z = G$. (Note, incidentally, that Z contains the unique involution in \tilde{G} .)

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Each of these groups comes with a “natural” two-dimensional unitary representation ρ , which is in fact self-dual (implying that $\rho \otimes \rho$ contains the trivial representation).

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We conclude that the graph is an extended ADE diagram. Indeed, the correspondence agrees with the one we just observed for the rotation groups.

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On comparing their work, each of them had missed a different infinite family. So it was clearly an ADE problem, as I will now describe.

Root systems

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Note that

- ▶ $2(v \cdot w) / (v \cdot v) \times 2(v \cdot w) / (w \cdot w) \leq 4$ by Cauchy–Schwarz, so if there are roots of different lengths then the ratio of their squared lengths is 2 or 3.

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- ▶ $\sigma_v(w) = w - 2(v \cdot w)/(v \cdot v)v$, an integer linear combination of v and w . From this, it can be shown that R spans a lattice (a **root lattice**).

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It can be shown that there is a basis consisting of roots with non-positive inner products. If G is the Gram matrix, then (after normalisation) we have $G = 2I - A$, where A is the adjacency matrix of a graph. Since G is positive definite, A has greatest eigenvalue less than 2.

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Thus, if the root system is indecomposable (that is, the graph is connected), it is an ADE diagram. Moreover, the graph determines the root system.

From the icosahedron to E_8

Is there a direct connection between the 3-dimensional rotation groups and the root systems, underlying the McKay correspondence? A beautiful construction was found recently by Pierre Dechant, using Clifford algebras; but I cannot describe it here. I merely note one small piece of numerology: the number of roots in the E_8 root system (240) is twice the number of rotations and reflections of the icosahedron.

Star-closed sets

Let A be the adjacency matrix of a graph with least eigenvalue -2 . Then $A + 2I$ is positive semidefinite, and so is the matrix of inner products of a set of vectors in \mathbb{R}^n , where n is the multiplicity of -2 as an eigenvalue. Clearly any two of these vectors make an angle 90° or 60° .

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Now a geometric argument shows that a set of lines through the origin in \mathbb{R}^n , in which any two lines make angle 90° or 60° , and is maximal with respect to this property, is **star-closed**: that is, if two lines in the set make angle 60° , then the third line in their plane at 60° to both is also in the set.

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Taking vectors of fixed length on the lines in such a star-closed set, we obtain a root system!

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The paper containing this theorem (with Goethals, Seidel, and Ernest Shult) is one of my most cited.

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