## Graphs on groups, rings, and maybe YBE solutions

#### Peter J. Cameron, University of St Andrews



Groups, Rings and YBE Blankenberge, 21 June 2023

But two years ago I was involved in an exciting adventure concerning graphs on groups, rings, and other algebraic structures, leading a research discussion in India (remotely – this was at the start of the pandemic) which has led to a lot of subsequent work.

But two years ago I was involved in an exciting adventure concerning graphs on groups, rings, and other algebraic structures, leading a research discussion in India (remotely – this was at the start of the pandemic) which has led to a lot of subsequent work.

So when I was invited to speak here, I hoped to apply some of those ideas to a different kind of algebraic set-up, set-theoretic solutions to the YBE.

But two years ago I was involved in an exciting adventure concerning graphs on groups, rings, and other algebraic structures, leading a research discussion in India (remotely – this was at the start of the pandemic) which has led to a lot of subsequent work.

So when I was invited to speak here, I hoped to apply some of those ideas to a different kind of algebraic set-up, set-theoretic solutions to the YBE.

I haven't got much to say on this yet but I hope that something interesting may develop.

## Introduction

The connection between graphs and algebraic structures goes back to Cayley in the 19th century.

## Introduction

The connection between graphs and algebraic structures goes back to Cayley in the 19th century. I will not be talking about Cayley graphs. My topic is graphs which more directly reflect the algebraic structure in question. The prototype is the commuting graph of a finite group G, where the vertex set is G (or possibly some subset), and g and hare joined by an edge if they commute.

## Introduction

The connection between graphs and algebraic structures goes back to Cayley in the 19th century.

I will not be talking about Cayley graphs. My topic is graphs which more directly reflect the algebraic structure in question. The prototype is the commuting graph of a finite group G, where the vertex set is G (or possibly some subset), and g and h are joined by an edge if they commute.

This was used by Brauer and Fowler in 1955 to show that there are only finitely many finite simple groups with a given involution centraliser, one of the basic results in the Classification of Finite Simple Groups, leading to a large amount of work characterising particular simple groups by their involution centralisers, and yielding several new sporadic simple groups along the way.

## Remarks

Brauer and Fowler had to assume that their simple group had even order, since Burnside's conjecture had not yet been proved at this point.

## Remarks

Brauer and Fowler had to assume that their simple group had even order, since Burnside's conjecture had not yet been proved at this point.

In the commuting graph, the closed neighbourhood of a vertex *g* is the centraliser of *g*. Graph theory tells us that we can bound the number of vertices by bounding the diameter and valency. (The diameter is bounded after removing the identity, since it is joined to all other vertices.)

## Remarks

Brauer and Fowler had to assume that their simple group had even order, since Burnside's conjecture had not yet been proved at this point.

In the commuting graph, the closed neighbourhood of a vertex *g* is the centraliser of *g*. Graph theory tells us that we can bound the number of vertices by bounding the diameter and valency. (The diameter is bounded after removing the identity, since it is joined to all other vertices.)

In fact, the word "graph" does not occur in the paper; but Brauer and Fowler carefully define the graph metric and use this instead. Since then, many different graphs on groups have been defined, including the generating graph (two vertices joined if they generate the group), the power graph (two vertices joined if one is a power of the other), and numerous variants. Since then, many different graphs on groups have been defined, including the generating graph (two vertices joined if they generate the group), the power graph (two vertices joined if one is a power of the other), and numerous variants. There are also graphs defined on rings, notably the zero-divisor graph, in which two non-zero elements are joined if their product is zero. Since then, many different graphs on groups have been defined, including the generating graph (two vertices joined if they generate the group), the power graph (two vertices joined if one is a power of the other), and numerous variants. There are also graphs defined on rings, notably the zero-divisor graph, in which two non-zero elements are joined if their product is zero.

Much of the literature on these graphs consists of calculating various graph-theoretic parameters of these graphs. I will not cover most of this.

I will talk just about groups, but similar questions can be asked for other structures.

1. Can we obtain new results about groups by considering these graphs?

- 1. Can we obtain new results about groups by considering these graphs?
- 2. Can we recognise old and new classes of groups by means of graphs?

- 1. Can we obtain new results about groups by considering these graphs?
- 2. Can we recognise old and new classes of groups by means of graphs?
- 3. Can we construct beautiful graphs in this way (possibly after some post-processing)?

- 1. Can we obtain new results about groups by considering these graphs?
- 2. Can we recognise old and new classes of groups by means of graphs?
- 3. Can we construct beautiful graphs in this way (possibly after some post-processing)?
- I will give examples of all three.

In 1904, Landau proved that there is a function F such that a finite group with k conjugacy classes has order at most F(k). In other words, there are only finitely many finite groups with a given number of conjugacy classes.

In 1904, Landau proved that there is a function F such that a finite group with k conjugacy classes has order at most F(k). In other words, there are only finitely many finite groups with a given number of conjugacy classes.

Many authors have worked on the problem of finding good bounds for F(k).

In 1904, Landau proved that there is a function F such that a finite group with k conjugacy classes has order at most F(k). In other words, there are only finitely many finite groups with a given number of conjugacy classes.

Many authors have worked on the problem of finding good bounds for F(k).

The solvable conjugacy class graph (for short, scc-graph) of a group has the conjugacy classes as vertices, with *C* and *D* adjacent if there exist  $c \in C$  and  $d \in D$  such that  $\langle c, d \rangle$  is solvable.

In 1904, Landau proved that there is a function F such that a finite group with k conjugacy classes has order at most F(k). In other words, there are only finitely many finite groups with a given number of conjugacy classes.

Many authors have worked on the problem of finding good bounds for F(k).

The solvable conjugacy class graph (for short, scc-graph) of a group has the conjugacy classes as vertices, with *C* and *D* adjacent if there exist  $c \in C$  and  $d \in D$  such that  $\langle c, d \rangle$  is solvable.

Recently, Parthajit Bhowal, Rajat Kanti Nath, Benjamin Sambale and I showed:

#### Theorem

There is a function f such that a finite group whose scc-graph has clique number k has order at most f(k).

The clique number of a graph is the size of the largest complete subgraph.

The clique number of a graph is the size of the largest complete subgraph. We used the Classification of Finite Simple Groups (CFSG) (a tool not available to Landau!) but only in a rather low-key way.

The clique number of a graph is the size of the largest complete subgraph.

We used the Classification of Finite Simple Groups (CFSG) (a tool not available to Landau!) but only in a rather low-key way.

Problem

Can the theorem be proved without CFSG?

The clique number of a graph is the size of the largest complete subgraph.

We used the Classification of Finite Simple Groups (CFSG) (a tool not available to Landau!) but only in a rather low-key way.

#### Problem

Can the theorem be proved without CFSG?

Also in contrast to Landau's case, no explicit bounds are known for f(k).

The clique number of a graph is the size of the largest complete subgraph.

We used the Classification of Finite Simple Groups (CFSG) (a tool not available to Landau!) but only in a rather low-key way.

#### Problem

Can the theorem be proved without CFSG?

Also in contrast to Landau's case, no explicit bounds are known for f(k).

#### Problem Find such bounds!

There are two natural ways to define classes of groups from graphs:

There are two natural ways to define classes of groups from graphs:

Choose a class of graphs (such as perfect graphs, cographs, chordal graphs, threshold graphs, split graphs, ...), and a type *t* of graph on groups, and ask: *For which groups G does* t(G) belong to the chosen graph class?

There are two natural ways to define classes of groups from graphs:

- Choose a class of graphs (such as perfect graphs, cographs, chordal graphs, threshold graphs, split graphs, ...), and a type *t* of graph on groups, and ask: *For which groups G does* t(G) belong to the chosen graph class?
- 2. Choose two types of graph on groups, say  $t_1$  and  $t_2$ , so that  $t_1(G)$  is an induced subgraph of  $t_2(G)$ , and ask: For which groups G is  $t_1(G) = t_2(G)$ ?

There are two natural ways to define classes of groups from graphs:

- Choose a class of graphs (such as perfect graphs, cographs, chordal graphs, threshold graphs, split graphs, ...), and a type *t* of graph on groups, and ask: *For which groups G does* t(G) belong to the chosen graph class?
- 2. Choose two types of graph on groups, say  $t_1$  and  $t_2$ , so that  $t_1(G)$  is an induced subgraph of  $t_2(G)$ , and ask: For which groups G is  $t_1(G) = t_2(G)$ ?

There are several examples of each in the literature. I will concentrate on the second.

### Two examples

We have seen the commuting graph ( $g \sim h$  if gh = hg) and the power graph ( $g \sim h$  if one of g and h is a power of the other). Between them is the enhanced power graph, with  $g \sim h$  if there exists k such that g and h are powers of k.

## Two examples

We have seen the commuting graph ( $g \sim h$  if gh = hg) and the power graph ( $g \sim h$  if one of g and h is a power of the other). Between them is the enhanced power graph, with  $g \sim h$  if there exists k such that g and h are powers of k.

Proposition

Let G be a finite group.

1. The power graph of G is equal to the enhanced power graph if and only if G contains no two commuting subgroups of distinct prime orders.

## Two examples

We have seen the commuting graph ( $g \sim h$  if gh = hg) and the power graph ( $g \sim h$  if one of g and h is a power of the other). Between them is the enhanced power graph, with  $g \sim h$  if there exists k such that g and h are powers of k.

#### Proposition

Let G be a finite group.

- 1. The power graph of G is equal to the enhanced power graph if and only if G contains no two commuting subgroups of distinct prime orders.
- 2. The enhanced power graph of G is equal to the commuting graph if and only if G contains no two commuting subgroups of the same prime order.

I will briefly discuss the two classes.

## Two classes of groups

The first class consists of EPPO groups, those in which every element has prime power order. (In other terminology these are groups whose Gruenberg–Kegel graph is null.) After pioneering work by Higman on solvable groups in the 1950s and Suzuki on simple groups in the 1960s, they were all determined by Brandl in a somewhat obscure paper in 1981.

### Two classes of groups

The first class consists of EPPO groups, those in which every element has prime power order. (In other terminology these are groups whose Gruenberg-Kegel graph is null.) After pioneering work by Higman on solvable groups in the 1950s and Suzuki on simple groups in the 1960s, they were all determined by Brandl in a somewhat obscure paper in 1981. The second class consists of groups containing no subgroup  $C_p \times C_p$  for p prime; in other words, all Sylow subgroups are cyclic or (if p = 2) generalized quaternon. Those with all Sylow subgroups cyclic are metacyclic of known structure; the others are determined by theorems of Glauberman and Gorenstein-Walter.

## Two classes of groups

The first class consists of EPPO groups, those in which every element has prime power order. (In other terminology these are groups whose Gruenberg-Kegel graph is null.) After pioneering work by Higman on solvable groups in the 1950s and Suzuki on simple groups in the 1960s, they were all determined by Brandl in a somewhat obscure paper in 1981. The second class consists of groups containing no subgroup  $C_p \times C_p$  for p prime; in other words, all Sylow subgroups are cyclic or (if p = 2) generalized quaternon. Those with all Sylow subgroups cyclic are metacyclic of known structure; the others are determined by theorems of Glauberman and Gorenstein-Walter.

All these results are without using CFSG.

The deep commuting graph

We heard about the **Bogomolov multiplier** from Geoffrey Janssens yesterday; it has a role here too.

## The deep commuting graph

We heard about the Bogomolov multiplier from Geoffrey Janssens yesterday; it has a role here too. The deep commuting graph of *G* is the graph with vertex set *G* in which *x* and *y* are joined if and only if their preimages in every central extension of *G* commute.

## The deep commuting graph

We heard about the **Bogomolov multiplier** from Geoffrey Janssens yesterday; it has a role here too.

The deep commuting graph of *G* is the graph with vertex set *G* in which *x* and *y* are joined if and only if their preimages in every central extension of *G* commute.

The deep commuting graph is contained in the commuting graph (in the sense of spanning subgraph, that is, its edge set is a subset of that of the commuting graph), and contains the enhanced power graph (since a central extension of a cyclic group is abelian). Bojan Kuzma and I investigated this graph, and proved (among other things)

#### Theorem

Let G be a finite group. Then the deep commuting graph is equal to the commuting graph if and only if the Bogomolov and Schur multipliers of G coincide. Bojan Kuzma and I investigated this graph, and proved (among other things)

#### Theorem

Let G be a finite group. Then the deep commuting graph is equal to the commuting graph if and only if the Bogomolov and Schur multipliers of G coincide.

Hence if *G* is simple then its commuting and deep commuting graphs are equal if and only if its Schur multiplier is trivial.

Other classes definable from graphs in similar ways include

 mimimal non-abelian, non-nilpotent, or non-solvable groups;

Other classes definable from graphs in similar ways include

- mimimal non-abelian, non-nilpotent, or non-solvable groups;
- Dedekind groups (those with all subgroups normal);

Other classes definable from graphs in similar ways include

- mimimal non-abelian, non-nilpotent, or non-solvable groups;
- Dedekind groups (those with all subgroups normal);
- 2-Engel groups (those satsfying the commutator identity [g, h, h] = 1).

Other classes definable from graphs in similar ways include

- mimimal non-abelian, non-nilpotent, or non-solvable groups;
- Dedekind groups (those with all subgroups normal);
- 2-Engel groups (those satsfying the commutator identity [g, h, h] = 1).

In many other cases, work is in progress. For example, the power graph of any finite group is perfect (that is, every induced subgraph has clique number equal to chromatic number): this condition is equivalent to forbidding odd cycles (of length greater than 3) and their complements as induced subgraphs, according to the Strong Perfect Graph Theorem.

### More on perfect graphs

There is no analogue for the enhanced power graph or commuting graph: these are universal (every finite graph occurs as an induced subgraph). We do not know which groups have one or other of these graphs perfect (this has been studied for the commuting graph by Britnell and Gill, who found all *perfect* groups for which this graph is perfect).

### More on perfect graphs

There is no analogue for the enhanced power graph or commuting graph: these are universal (every finite graph occurs as an induced subgraph). We do not know which groups have one or other of these graphs perfect (this has been studied for the commuting graph by Britnell and Gill, who found all *perfect* groups for which this graph is perfect). Veronica Phan and I proved that the enhanced power graph of any finite group is weakly perfect – this means that the graph itself has clique number equal to chromatic number, though this may fail for induced subgraphs.

# 3. Finding beautiful graphs

If you choose your favourite group and ask the computer to construct one of these graphs and tell you how many automorphisms it has, you are in for a shock. For example, the commuting group of the alternating group  $A_5$  (a group of order 60) has 477090132393463570759680000 automorphisms. In fact, most of this is rubbish; in the case of  $A_5$  it is all rubbish. But sometimes there is a jewel buried in the heart of the lotus flower.

# 3. Finding beautiful graphs

If you choose your favourite group and ask the computer to construct one of these graphs and tell you how many automorphisms it has, you are in for a shock. For example, the commuting group of the alternating group  $A_5$  (a group of order 60) has 477090132393463570759680000 automorphisms. In fact, most of this is rubbish; in the case of  $A_5$  it is all rubbish. But sometimes there is a jewel buried in the heart of the lotus flower.

Two vertices x, y of a graph are called twins if they have the same neighbours, except possibly one another. If two vertices are twins, then the map interchanging them and fixing everything else is a graph automorphism.

# 3. Finding beautiful graphs

If you choose your favourite group and ask the computer to construct one of these graphs and tell you how many automorphisms it has, you are in for a shock. For example, the commuting group of the alternating group  $A_5$  (a group of order 60) has 477090132393463570759680000 automorphisms. In fact, most of this is rubbish; in the case of  $A_5$  it is all rubbish. But sometimes there is a jewel buried in the heart of the lotus flower.

Two vertices x, y of a graph are called twins if they have the same neighbours, except possibly one another. If two vertices are twins, then the map interchanging them and fixing everything else is a graph automorphism.

Our graphs on groups tend to have many pairs of twins. If x and y generate the same cyclic subgroup of G, then they are twins in all the graphs mentioned so far, and essentially all others as well.

## Twin reduction

Twin reduction is the process of choosing a pair of twins and identifying them, repeating the process until no twins remain. The resulting graph is (up to isomorphism) independent of the way the reduction is carried out. I will call it the cokernel of the original graph (no connection with homological algebra implied).

## Twin reduction

Twin reduction is the process of choosing a pair of twins and identifying them, repeating the process until no twins remain. The resulting graph is (up to isomorphism) independent of the way the reduction is carried out. I will call it the cokernel of the original graph (no connection with homological algebra implied).

A graph is called a cograph if it has no induced subgraph isomorphic to the 4-vertex path. Cographs form the smallest class of graphs which can be built from 1-vertex graphs by the operations of disjoint union and complementation.

## Twin reduction

Twin reduction is the process of choosing a pair of twins and identifying them, repeating the process until no twins remain. The resulting graph is (up to isomorphism) independent of the way the reduction is carried out. I will call it the cokernel of the original graph (no connection with homological algebra implied).

A graph is called a cograph if it has no induced subgraph isomorphic to the 4-vertex path. Cographs form the smallest class of graphs which can be built from 1-vertex graphs by the operations of disjoint union and complementation.

### Proposition

A graph is a cograph if and only if its cokernel is the 1-vertex graph.

### The search

### The above result gives added significance to the question:

### Problem

Given a type t of graph defined on groups, for which groups G is t(G) a cograph?

### The search

The above result gives added significance to the question:

### Problem

Given a type t of graph defined on groups, for which groups G is t(G) a cograph?

Partial answers are known in some cases. In particular, Pallabi Manna, Ranjit Mehatari and I have determined the finite simple groups whose power graph is a cograph; Xuanlong Ma, Natalia Maslova and I have done the same for the commuting graph.

### The search

The above result gives added significance to the question:

### Problem

Given a type t of graph defined on groups, for which groups G is t(G) a cograph?

Partial answers are known in some cases. In particular, Pallabi Manna, Ranjit Mehatari and I have determined the finite simple groups whose power graph is a cograph; Xuanlong Ma, Natalia Maslova and I have done the same for the commuting graph. The simplest results are for what I will call the difference graph, whose edges are those in the enhanced power graph but not in the power graph.

Empirically we find four cases for the difference graph of a simple group:

the difference graph has no edges (these are the EPPO groups defined earlier);

- the difference graph has no edges (these are the EPPO groups defined earlier);
- the difference graph is a cograph, so its cokernel has a single vertex;

- the difference graph has no edges (these are the EPPO groups defined earlier);
- the difference graph is a cograph, so its cokernel has a single vertex;
- the cokernel of the difference graph has many very small connected components, all isomorphic;

- the difference graph has no edges (these are the EPPO groups defined earlier);
- the difference graph is a cograph, so its cokernel has a single vertex;
- the cokernel of the difference graph has many very small connected components, all isomorphic;
- the cokernel is connected; its full automorphism group is the same as the automorphism group of the simple group with which we began; and the graph has nice properties (for example, large girth).





In the first three cases, the wind blows away all the lotus petals and nothing remains. But in the fourth case, we have discovered a jewel.



In the first three cases, the wind blows away all the lotus petals and nothing remains. But in the fourth case, we have discovered a jewel.

For example, if *G* is the Matheu group  $M_{11}$ , then the cokernel of the difference graph is bipartite, with blocks of size 165 and 220; the valencies of vertices in the two blocks are 4 and 3 respectively; the graph is connected, with diameter and girth 10; and its automorphism group is  $M_{11}$ .



In the first three cases, the wind blows away all the lotus petals and nothing remains. But in the fourth case, we have discovered a jewel.

For example, if *G* is the Matheu group  $M_{11}$ , then the cokernel of the difference graph is bipartite, with blocks of size 165 and 220; the valencies of vertices in the two blocks are 4 and 3 respectively; the graph is connected, with diameter and girth 10; and its automorphism group is  $M_{11}$ . More exploration remains to be done ...

To someone with a hammer, everything is a nail.

To someone with a hammer, everything is a nail.

Can any of these graph-theoretic approaches tell us anything about set-theoretic solutions of the YBE? I have only very recently begun to think about this, so I haven't got very far; I would appreciate suggestions!

To someone with a hammer, everything is a nail.

Can any of these graph-theoretic approaches tell us anything about set-theoretic solutions of the YBE? I have only very recently begun to think about this, so I haven't got very far; I would appreciate suggestions!

To begin at the beginning: the set-theoretic Yang–Baxter equation is an equation for a function  $r : X \times X \rightarrow X \times X$  satisfying

 $r_{12}r_{23}r_{12}=r_{23}r_{12}r_{23},$ 

where this equation refers to maps on  $X \times X \times X$ , and  $r_{ij}$  replaces the pair  $(x_i, x_j)$  by the pair of coordinates of  $r(x_i, x_j)$ .

To someone with a hammer, everything is a nail.

Can any of these graph-theoretic approaches tell us anything about set-theoretic solutions of the YBE? I have only very recently begun to think about this, so I haven't got very far; I would appreciate suggestions!

To begin at the beginning: the set-theoretic Yang–Baxter equation is an equation for a function  $r : X \times X \rightarrow X \times X$  satisfying

 $r_{12}r_{23}r_{12}=r_{23}r_{12}r_{23},$ 

where this equation refers to maps on  $X \times X \times X$ , and  $r_{ij}$  replaces the pair  $(x_i, x_j)$  by the pair of coordinates of  $r(x_i, x_j)$ . There are three additional conditions which are sometimes imposed:

To someone with a hammer, everything is a nail.

Can any of these graph-theoretic approaches tell us anything about set-theoretic solutions of the YBE? I have only very recently begun to think about this, so I haven't got very far; I would appreciate suggestions!

To begin at the beginning: the set-theoretic Yang–Baxter equation is an equation for a function  $r : X \times X \rightarrow X \times X$  satisfying

 $r_{12}r_{23}r_{12}=r_{23}r_{12}r_{23},$ 

where this equation refers to maps on  $X \times X \times X$ , and  $r_{ij}$  replaces the pair  $(x_i, x_j)$  by the pair of coordinates of  $r(x_i, x_j)$ . There are three additional conditions which are sometimes imposed:

• 
$$r(x,x) = (x,x)$$
 for all  $x \in X$ ;

# What about Yang-Baxter?

To someone with a hammer, everything is a nail.

Can any of these graph-theoretic approaches tell us anything about set-theoretic solutions of the YBE? I have only very recently begun to think about this, so I haven't got very far; I would appreciate suggestions!

To begin at the beginning: the set-theoretic Yang–Baxter equation is an equation for a function  $r : X \times X \rightarrow X \times X$  satisfying

 $r_{12}r_{23}r_{12}=r_{23}r_{12}r_{23},$ 

where this equation refers to maps on  $X \times X \times X$ , and  $r_{ij}$  replaces the pair  $(x_i, x_j)$  by the pair of coordinates of  $r(x_i, x_j)$ . There are three additional conditions which are sometimes imposed:

• r(x,x) = (x,x) for all  $x \in X$ ;

*r* is an involution (this implies that it is a bijection);

# What about Yang-Baxter?

To someone with a hammer, everything is a nail.

Can any of these graph-theoretic approaches tell us anything about set-theoretic solutions of the YBE? I have only very recently begun to think about this, so I haven't got very far; I would appreciate suggestions!

To begin at the beginning: the set-theoretic Yang–Baxter equation is an equation for a function  $r : X \times X \rightarrow X \times X$  satisfying

 $r_{12}r_{23}r_{12}=r_{23}r_{12}r_{23},$ 

where this equation refers to maps on  $X \times X \times X$ , and  $r_{ij}$  replaces the pair  $(x_i, x_j)$  by the pair of coordinates of  $r(x_i, x_j)$ . There are three additional conditions which are sometimes imposed:

- r(x,x) = (x,x) for all  $x \in X$ ;
- *r* is an involution (this implies that it is a bijection);
- *r* is non-degenerate (see next slide).

# Monoids and groups

As usual, an endomorphism of (X, r) is a self-map of X whose induced action on  $X^2$  commutes with r. An invertible endomorphism whose inverse is also an endomorphism is an automorphism. So we have an endomorphism monoid and an automorphism group.

# Monoids and groups

As usual, an endomorphism of (X, r) is a self-map of X whose induced action on  $X^2$  commutes with r. An invertible endomorphism whose inverse is also an endomorphism is an automorphism. So we have an endomorphism monoid and an automorphism group.

Said otherwise, automorphisms preserve the orbits of r (in the sense of dynamics), the result of iterating r on a starting pair. If r is bijective, these are the automorphisms of the group it generates (since X is finite).

# Monoids and groups

As usual, an endomorphism of (X, r) is a self-map of X whose induced action on  $X^2$  commutes with r. An invertible endomorphism whose inverse is also an endomorphism is an automorphism. So we have an endomorphism monoid and an automorphism group.

Said otherwise, automorphisms preserve the orbits of r (in the sense of dynamics), the result of iterating r on a starting pair. If r is bijective, these are the automorphisms of the group it generates (since X is finite).

The Yang–Baxter monoid and group have completely different definitions; how are they related?

We can write r(x, y) as  $(\lambda_x(y), \rho_y(x))$ , where, for any  $x, y \in X$ , the functions  $\lambda_x$  and  $\rho_y$  map X to X. We say that our solution is **non-degenerate** if these functions are bijections for all choices of x and y.

We can write r(x, y) as  $(\lambda_x(y), \rho_y(x))$ , where, for any  $x, y \in X$ , the functions  $\lambda_x$  and  $\rho_y$  map X to X. We say that our solution is non-degenerate if these functions are bijections for all choices of x and y.

Now we regard the permutations  $\lambda_x$  and  $\rho_y$  as generators of a group G(r) acting on X. Warning: It is customary to regard the  $\lambda_x$  as acting on the left and the  $\rho_y$  on the right: as a mnemonic, r(x, y) is often written as  $({}^xy, x^y)$ .

We can write r(x, y) as  $(\lambda_x(y), \rho_y(x))$ , where, for any  $x, y \in X$ , the functions  $\lambda_x$  and  $\rho_y$  map X to X. We say that our solution is non-degenerate if these functions are bijections for all choices of x and y.

Now we regard the permutations  $\lambda_x$  and  $\rho_y$  as generators of a group G(r) acting on X. Warning: It is customary to regard the  $\lambda_x$  as acting on the left and the  $\rho_y$  on the right: as a mnemonic, r(x, y) is often written as  $({}^xy, x^y)$ .

The YBE and the extra conditions imply that the  $\rho$ s can be written in terms of the  $\lambda$ s, and *vice versa*; so the groups generated by the  $\lambda$ s and by the  $\rho$ s are equal. This is the Yang–Baxter permutation group associated with the solution.

We can write r(x, y) as  $(\lambda_x(y), \rho_y(x))$ , where, for any  $x, y \in X$ , the functions  $\lambda_x$  and  $\rho_y$  map X to X. We say that our solution is non-degenerate if these functions are bijections for all choices of x and y.

Now we regard the permutations  $\lambda_x$  and  $\rho_y$  as generators of a group G(r) acting on X. Warning: It is customary to regard the  $\lambda_x$  as acting on the left and the  $\rho_y$  on the right: as a mnemonic, r(x, y) is often written as  $({}^xy, x^y)$ .

The YBE and the extra conditions imply that the  $\rho$ s can be written in terms of the  $\lambda$ s, and *vice versa*; so the groups generated by the  $\lambda$ s and by the  $\rho$ s are equal. This is the Yang–Baxter permutation group associated with the solution. Note: we should certainly be open to relaxing the non-degeneracy condition and working with monoids rather than groups; but their theory is less developed.

### Connections

The representation theory of permutation groups is based on the relation between the permutation group and its centralizer algebra, using the double centralizer theory. Can something similar be done here? We have three objects in play, the monoid (or group) generated by r; the endomorphism monoid or automorphism group of (X, r); and the Yang–Baxter transformation monoid or permutation group.

## Connections

The representation theory of permutation groups is based on the relation between the permutation group and its centralizer algebra, using the double centralizer theory. Can something similar be done here? We have three objects in play, the monoid (or group) generated by r; the endomorphism monoid or automorphism group of (X, r); and the Yang–Baxter transformation monoid or permutation group.

#### Problem

What are the relations among these?

In the case of the trivial solution r(x, y) = (y, x), the YB group is trivial and the automorphism group is the symmetric group.

# Cayley graph

With the assumptions earlier, the YB permutation group is generated by the maps  $\lambda_x$ ; in other words, there is a map from *X* into Sym(*X*) whose image generates the YB permutation group.

With the assumptions earlier, the YB permutation group is generated by the maps  $\lambda_x$ ; in other words, there is a map from *X* into Sym(*X*) whose image generates the YB permutation group.

So we can construct the Cayley graph  $Cay(G, \{\lambda : x : x \in X\})$ , so the set *X* is both the domain of the permutation group and an index set for the edges through the identity in the Cayley graph.

With the assumptions earlier, the YB permutation group is generated by the maps  $\lambda_x$ ; in other words, there is a map from *X* into Sym(*X*) whose image generates the YB permutation group.

So we can construct the Cayley graph  $Cay(G, \{\lambda : x : x \in X\})$ , so the set *X* is both the domain of the permutation group and an index set for the edges through the identity in the Cayley graph.

What can we do with this set-up?

More questions:

 Silvia Properzi yesterday defined a graph from a skew brace. I think that several further analogues of graphs on groups can be defined by similar methods.

More questions:

- Silvia Properzi yesterday defined a graph from a skew brace. I think that several further analogues of graphs on groups can be defined by similar methods.
- Is it possible to use beautiful combinatorial objects (perhaps graphs on groups) to define interesting solutions of the YBE, or *vice versa*?

More questions:

- Silvia Properzi yesterday defined a graph from a skew brace. I think that several further analogues of graphs on groups can be defined by similar methods.
- Is it possible to use beautiful combinatorial objects (perhaps graphs on groups) to define interesting solutions of the YBE, or *vice versa*?

Suggestions welcome!

More questions:

- Silvia Properzi yesterday defined a graph from a skew brace. I think that several further analogues of graphs on groups can be defined by similar methods.
- Is it possible to use beautiful combinatorial objects (perhaps graphs on groups) to define interesting solutions of the YBE, or *vice versa*?

Suggestions welcome!



... for your attention.